

Testing the efficiency of adjacency algorithms for solving unit restricted models

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INTRODUCTION

Adjacency constraints – important part of spatial harvest scheduling models since GIS tools were developed

➡ legal constraints, environmental constraints etc.

Early solvers ➡ **limited number of variables and constraints** !

this can lead to a loss of efficiency in solving some problems (as discussed by Torres-Rojo and Brodie 1990).

the reduction of constraints less relevant (Crowe et al. 2003)

There are many possibilities how to add adjacency constraints into the model



Pairwise constraints



Very simple to create



High number of constraints



Constraints based on analytical algorithms

(Yoshimoto, Brodie 1994)



Low number of constraints



Mathematical modification is needed

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Computer memory [random-access memory] („CM“) usage

Pairwise constraints

Database with spatial information



Model



No „CM“ is used

Constraints based on analytical algorithms

Database with spatial information



Mathematical modification

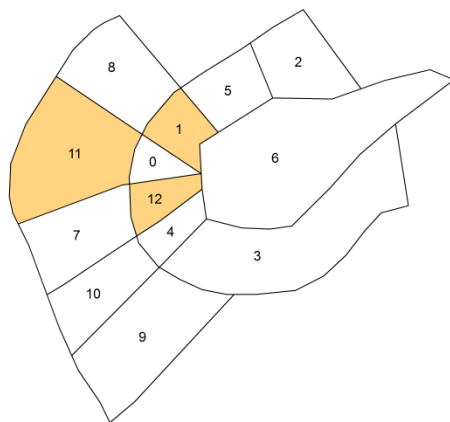


Model



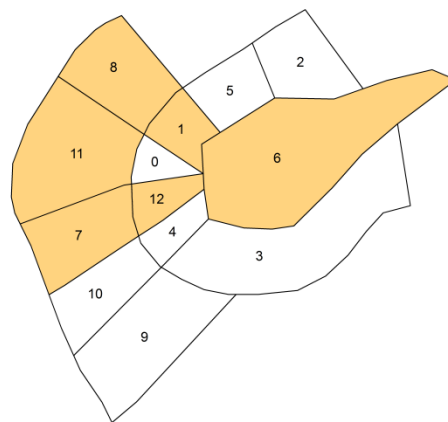
„CM“ is used

The effect of neighbourhood type



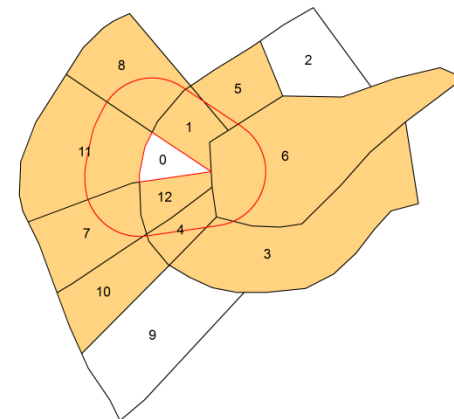
Neumann

3



Moore

6



Buffer 30 meters

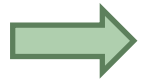
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The goal of the work



To compare time needed for creating and solving models with adjacency constraints:

- based on 3 different analytical algorithms + pairwise constraints
- for 3 different types of neighbourhood



Is it necessary to consume computer memory and time by using the analytical algorithms when the sophisticated softwares and powerful computers are available?



MATERIAL AND METHODS

- ➔ **738** randomly generated spatial structures (**1-738 polygons**)
- ➔ **2-3 optimization** were made for each spatial structure –**2,000 optimization** in total
- ➔ Totally **12** variants =
4 types of adjacency constraints × 3 types of neighbourhood



Gurobi optimization software was used for analysis



Personal computer Intel® Core™ i7-2600 CPU @ 3.40 GHz was used



The models were written in Java programming language

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Mathematical model

$$\max Z = \sum_{i=1}^n \sum_{p=1}^5 v_{ip} \cdot x_{ip}$$

$$\sum_{p=1}^5 x_{ip} \leq 1 \quad \forall i = 1, 2, \dots, n$$



Adjacency constraints

	Evaluated time			
	Type of adjacency constraints	Algorithm processing time	Constraints creating time	Solving time
$\mathbf{M} \cdot x \leq \mathbf{A} \cdot 1$ $\mathbf{M} = \mathbf{A} + \mathbf{B}$	Triangular adjacency matrix (TAM)			
	Row adjacency matrix (RAM)			
	Triangular row adjacency matrix (TRAM)			
$x_i + x_j \leq 1$	Pairwise constraints			

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Neighbourhood	Neighbours statistics		
	Mean	Standard deviation	Max / Min
Neumann	3.9	2.9	28 / 0
Moore	4.2	3.1	28 / 0
Buffer	7.0	5.3	44 / 0

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	Number of resulted constraints			
	TAM	RAM	TRAM	Pairwise constraints
Neumann	0 - 522	0 - 423	0 - 423	0 - 1,472
Moore	0 - 530	0 - 441	0 - 441	0 - 1,628
Buffer	0 - 620	0 - 527	0 - 527	0 - 2,778

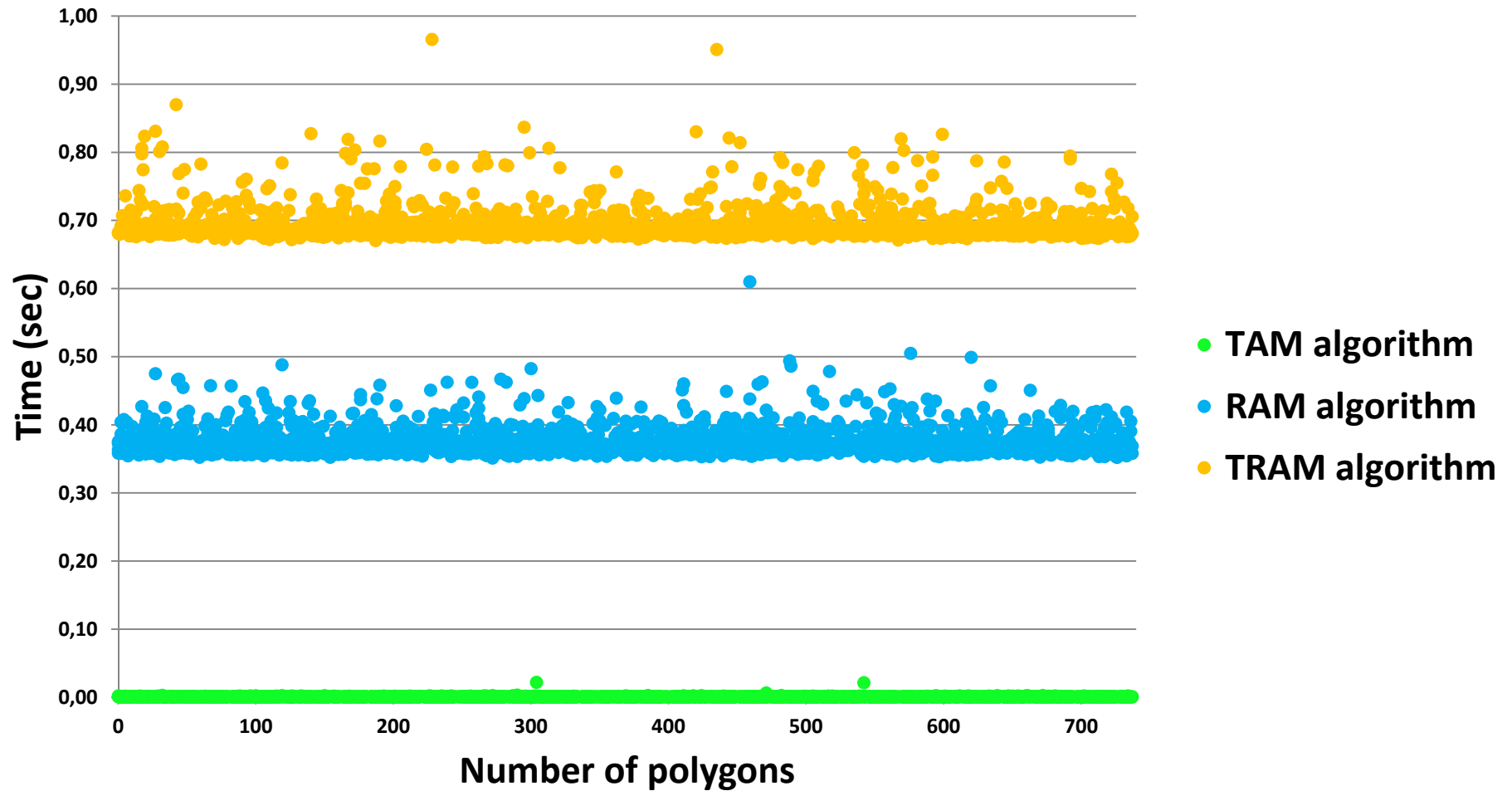
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PROCESSING TIME FOR DIFFERENT ALGORITHMS – Buffer neighbourhoods



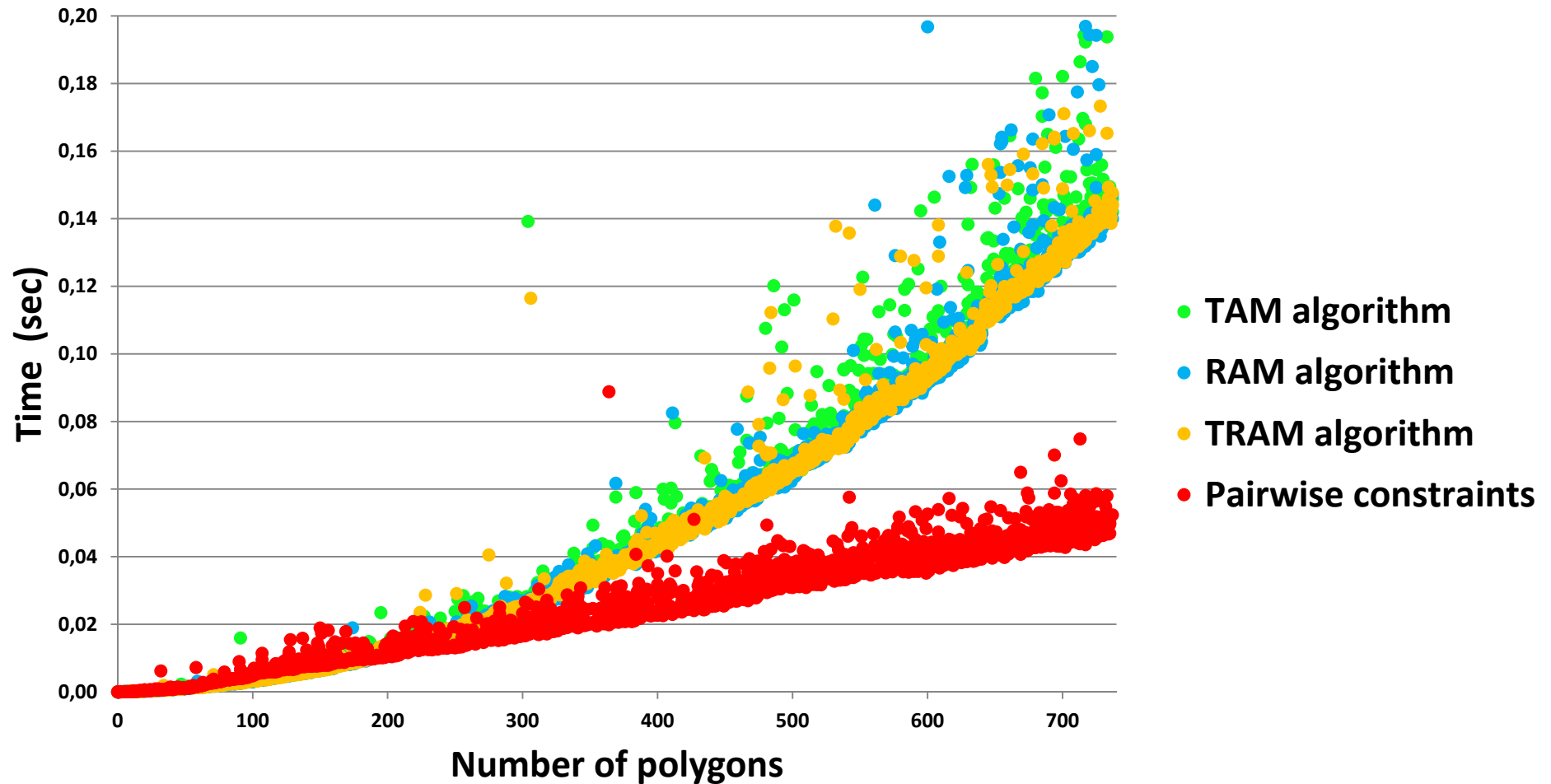
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CONSTRAINTS CREATING TIME FOR DIFFERENT ALGORITHMS – Buffer neighbourhoods



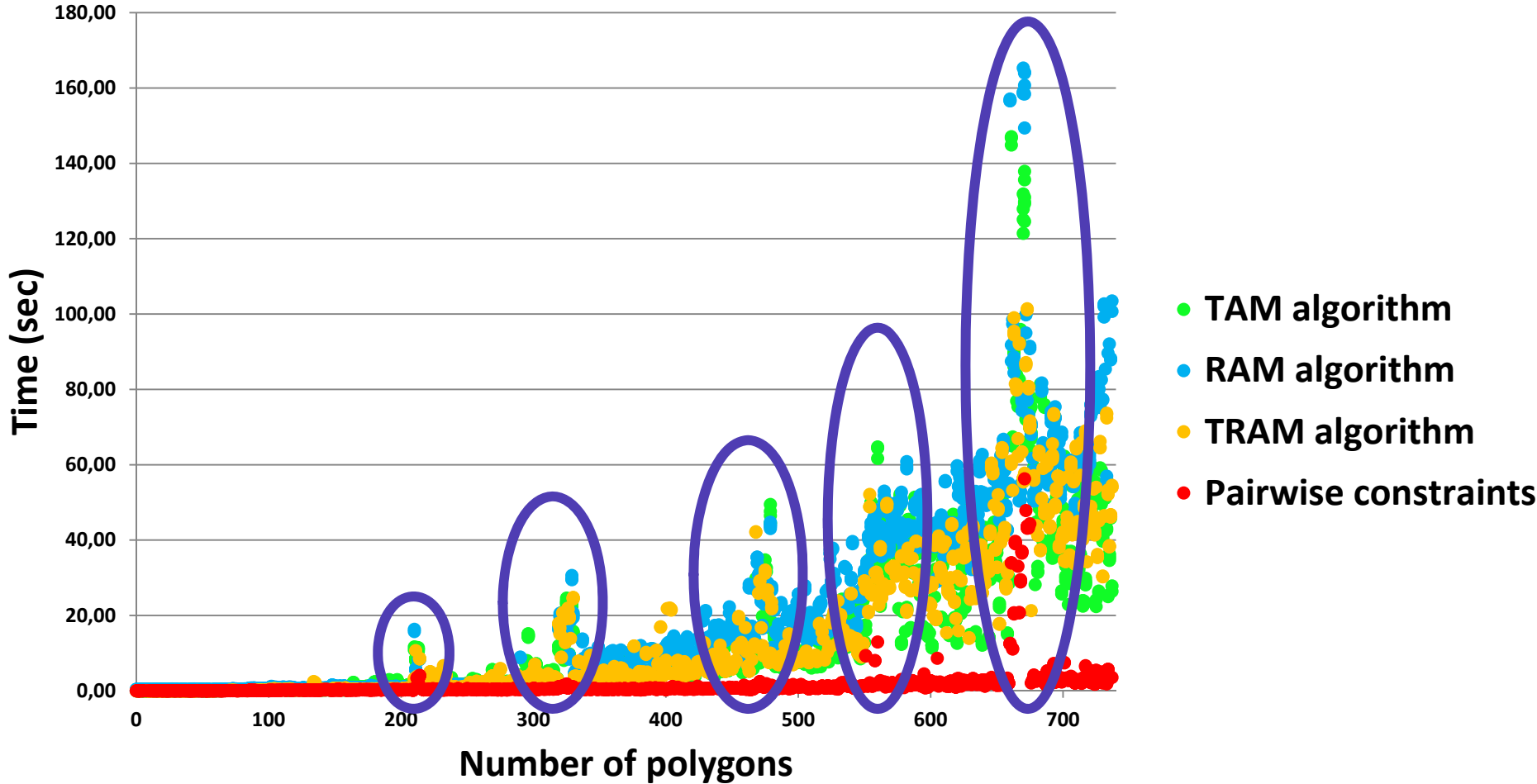
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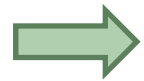
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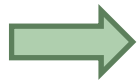
MODEL SOLVING TIME OF DIFFERENT ALGORITHMS – Buffer neighbourhoods



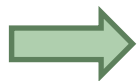
DISCUSSION AND CONCLUSION



Time needed for creating constraints in the model and solving is strongly related to the number of neighbours



Solving time depends not only on the number of polygons but also on the spatial structure



Analytical algorithms reduce the total number of constraints, however they can lead to the loss of efficiency of branch-and-cut algorithm for solving the model



Thank you for your attention!

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